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load shaft with

respect to the input

motor voltage can be

described by the

following first-order

transfer function  $\Theta(s)$

$K = (1.1.1) V_m (s) (\tau s$

$+ 1)$  where  $\Theta(s)$  is the

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or expand the scope of this unit by adding on other modules to teach an even wider range of control concepts. Instructors can thus expose ...

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approach to control systems allows for the creation of precise controllers for complex systems with higher order dynamics. These plants include both dynamically complex plants such as the linear inverted pendulum, and double pendulum, as well as plants such as the

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active suspension that  
require the use of  
both state space ...

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