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which must adapt to a controlled system with parameters which vary, or are initially uncertain. For

example, as an aircraft flies, its mass will slowly decrease as a result of fuel Solution Manual Adaptive

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$D(q^{-1})A(q^{-1})[T(t)(t+1)]$ (3.161) and the parameter adaptation algorithm satisfying the passivity condition will take the form: $\hat{\theta}(t+1) = \hat{\theta}(t) + F(t)e(t+1)$ (3.162) The equivalent feedback representation associated with the output error predictor using the above PAA is shown in Fig. 3.9.

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